Series SR90

%RH
SHIMADEN DIGITAL CONTROLLER



## BASIC FEATURES

- ☐ Multi-input and multi-range performance
- ☐ Large 20mm bright display (SR93)
- ☐ Readable from a distance and in a low light area
- ☐ 2-output heating and cooling control available
- ☐ RS232C or RS485 Interface available
- ☐ Dust and splash proof front panel equivalent to IP66
- ☐ A wide selection of additional functions (optional) is available to suit various needs.

**SPECIFICATIONS** Series SR90

■ Display RA (reverse action characteristic): Heating action (OUT1) and cooling action (OUT2) • Digital display: Measured value (PV)/7 segments red LED DA (direct characteristic): 2-stage heating action rating: Contact/1a 240V AC 2A (resistive load) 4 digits Target set value (SV)/7 segments green • Type of control/rating: 1.2A (inductive load) LED 4 digits  $\pm (0.3\%FS + 1 \text{ digit})$ (Common to Output 1 and 2): SSR drive voltage/12V±1.5V DC • Display accuracy: (Maximum load current 30mA) Excluding reference contact temperature Current/4~20mA DC (Maximum load compensation accuracy of thermocouple resistance 600Ω) Voltage/0~10V DC (Maximum load Accuracy of readings lower than −100°C of thermocouples K, T, U inputs is  $\pm 0.7\%$  FS. current 2mA) Accuracy guarantee not applicable to 400°C (752°F) and below of B Control output resolution: Control output 1: approx. 0.0125% (1/8000) Control output 2: approx. 0.5% (1/200) Control output 1 thermocouple. • Display accuracy maintaining range: Proportional band (P): OFF, 0.1~999.9% (ON-OFF action by OFF)  $23^{\circ}C \pm 5^{\circ}C (18\sim28^{\circ}C)$ Integral time (I): OFF, 1~6000 seconds (P or PD action by OFF) Depends on measuring range (0.001, 0.01, • Display resolution: Derivative time (D): OFF, 1~3600 seconds 0.1 and 1)(P or PI action by OFF) • Measured value display range: -10%~110% of measuring range Set value function: OFF, 0.01~1.00 • Display updating cycle: 0.25 seconds ON-OFF hysteresis: 1~999 units (Effective when P=OFF) Action display/color: 7 type, LED lamp display Control output (OUT1, OUT2)/Green Manual reset: -50.0~50.0% (Effective when I=OFF) Event (EV1, EV2)/Orange Higher/lower limit output limiter: Lower limit 0.0~99.9%, higher limit Auto tuning/Green 0.1~100.0% (Lower limit value < Higher Manual control output (MAN)/Green Set value bias, communication Proportional cycle: 1~120 seconds (for contact and SSR drive (SB/COM)/Green voltage output) ■ Setting Control output 2 (option) Proportional band (P): OFF, 0.1~999.9% • Setting method: By operating 4 keys (②, ▼, ▲ (ON-OFF action by OFF) and (ENT) on the front panel Integral time (I): OFF, 1~6000 seconds • Target value setting range: Same as measuring range (within setting (P or PD action by OFF) limiter) Derivative time (D): OFF, 1~3600 seconds • Setting limiter: Individual setting for higher and lower (P or PI action by OFF) limits, any value is selectable within Set value function: OFF, 0.01~1.00 measuring range (Lower limit ON-OFF hysteresis: 1~999 units (Effective when P=OFF) value<Higher limit value) Dead band: -1999~5000 units (Overlap with a negative ■ Input Selectable from multiple (TC, Pt, mV), • Type of input: Lower limit 0.0~99.9%, higher limit Higher/lower limit output limiter: voltage (V) and current (mA) 0.1~100.0% (Lower limit value < Higher B, R, S, K, E, J, T, N, PL II, Wre5-26 (U, L • Thermocouple: limit value) (DIN 43710)} 1~120 seconds (for contact and SSR drive Proportional cycle: 500kΩ minimum Input impedance: voltage output)  $100\Omega$  maximum External resistance tolerance: Manual control Burnout function: Standard feature (up scale) Reference junction compensation accuracy:
± 1°C (within the accuracy maintaining 0.0~100.0% Output setting range: Setting resolution: 0.1% Manual ↔ auto switching: Balanceless bumpless (within proportional range  $(23 \pm 5^{\circ}C)$ ± 2°C (between 5 and 45°C of ambient • Soft start: OFF, 1~100 seconds temperature) SV value in execution • AT point: • R.T.D.: Pt100/JPt100, 3-wire type • Control output characteristic: RA (reverse action characteristic)/DA Normal current: 0.25 mA (direct action characteristic) switching by Lead wire tolerance:  $5\Omega$  maximum/wire (3 lead wires should front key or communication have the same resistance.) RA (heating/cooling)/DA (2 stage heating) With 2 outputs: Voltage mV: -10~10, 0~10, 0~20, 0~50, 10~50, Contact output isolated from all. • Isolation: 0~100mv DC Analog output not insulated from SSR drive -1~1, 0~1, 0~2, 0~5, 1~5, 0~10V V: voltage, current and voltage but insulated 500kΩ minimum Input impedance: from others. (In case another output is also 0~20, 4~20mA DC • Current mA: SSR drive voltage, current or voltage, Receiving impedance:  $250\Omega$ two outputs are not insulated from • Input scaling function: Scaling possible for voltage (mV, V) or each other.) current (mA) input ■ Event output (option) Scaling range: -1999~9999 counts • Number of event points: 2 points of EV1 and EV2 10~5000 counts Span: Selectable from the following 9 types for Types: Position of decimal point: None, 1, 2 and 3 digits on the right of EV1 and EV2: decimal point No selection Sampling cycle: 0.25 seconds H⊿ H igher limit deviation • PV bias: -1999~2000 units • PV filter: ∠ d' Lower limit deviation 0~100 seconds

**□** d' Outside higher/lower limit deviations **∠** W ithin higher/lower limit deviations

HR H igher limit absolute value ∠ A Lower limit absolute value 50 Scaleover

Event setting range:

Heater break/loop alarm Absolute values (both higher limit and lower limit): Within measuring range

Deviations (both higher limit and lower limit): -1999~2000 units Higher/lower limit deviations (within/outside): 0~2000 units

■ Control

• Isolation:

Control mode

With 1 output: Expert PID control with auto tuning function

others

RA (reverse action characteristic): Heating action DA (direct action characteristic): Cooling action

Control input not insulated from system, set

value bias, and CT input but insulated from

Expert PID control with auto tuning function + With 2 outputs:

PID control

PID (output 1) + PID (output 2)

ON-OFF action ■ Analog output (option) • Event action: • Number of output points: • Hysteresis: 1~999 units 1 point Standby action: Selectable from the following 4 types Selectable from measured value, target • Type of analog output: value (SV in execution), control output 1 EV1 and EV2: 1 Without standby action. 2 Standby when power is applied. and control output 2. 3 Standby when power is applied and Output signal/rating: 4~20mA DC/Maximum load resistance 300Ω when SV value in execution is changed. 0~10V DC/Maximum load current 2mA 4 Control mode without standby action (No 0~10mV DC/Output resistance 10Ω Output scaling: Measured value, target value: Within alarm is output at the time of abnormal input). measuring range (inversed scaling possible) Control output 1 and 2 0.0~100.0% • Output type/rating: Contact (1a × 2 points common)/240V AC 1A (resistive load) (inversed scaling possible) Output updating cycle: 0.25 seconds Output accuracy:  $\pm 0.3\%$  FS (with respect to displayed value) Heater break/heater loop alarm (option) Approx. 0.01% (1/10000) Output resolution: Break/loop detection only for OUT1 (Selectable when output type is • Output updating cycle: 0.25 seconds Analog output insulated from system and contact or SSR drive voltage) Isolation: 30A, 50A to be designated when CT is Current capacity: inputs but not insulated from control output ordered. except contact output. Alarm action: Heater current is detected by external CT ■ General specifications provided as an accessory. • Data storage: Non-volatile memory (EEPROM) When heater break is detected while control • Environmental conditions for instrument operation: output is ON=Alarm output ON Temperature: -10~50°C When heater loop alarm is detected while Humidity: 90% RH or less (no dew condensation) control output is OFF=Alarm output ON Height: 2000m from the sea level or lower OFF, 0.1~50.0A (Alarm action is stopped Category: Current setting range: П by setting OFF) Degree of pollution: • Setting resolution: -20~65°C 0.1AStorage temperature: • Current display range: 0.0~55.0A Supply voltage: Either 100-240V AC±10% 50/60Hz or 24V AC/DC±10% to be designated. ±2.0A (Sine wave at 50Hz) Display accuracy: Minimum time to identify action: 0.25 seconds (every 0.5 seconds) common • Power consumption: SR91: 100-240VAC 11VA maximum for to ON and OFF AC; 6W for DC 24V; 7VA for AC 24V Alarm retention mode: Selectable from lock (to retain) and real SR92, SR93 and SR94: 100-240VAC 15VA maximum for AC; 8W for DC (not to retain). Selectable from without (OFF) and with 24V; 9VA for AC 24V Standby action: 50 dB or higher in normal mode (50/60 Hz) (ON). • Input/noise removal ratio: Sampling cycle: 0.5 seconds 130 dB or higher in common mode CT input not insulated from system and (50/60 Hz) Isolation: Safety: IEC1010 and EN61010-1 EMC: EN61326 other inputs but insulated from the others. Applicable standards: ■ Set value bias (option) Between input/output terminals and power terminal 500V DC 20M $\Omega$  or above; -1999~5000 units Insulation resistance: Setting range: Non-voltage contact or open collector (level • Action input: action) about 5V DC, 1mA maximum Between input/output terminals and • Minimum level retention time: 0.15 seconds protective conductor terminal 500V DC Isolation: Action input not insulated from system and  $20M\Omega$  or above other inputs but insulated from others • Dielectric strength: Between input/output terminals and power ■ Communication function (option) terminal 2300V AC/minute; Between • Type of communication: RS-232C, RS-485 power terminal and protective conductor • Communication system: RS-232C 3-line type half duplex system terminal 1500V AC/minute RS-485 2-line type half duplex system • Protective structure: Only front panel has dust-proof and drip-{RS-485 is of half-duplex multi-drop (bus) proof structure equivalent to IP66. PPO resin molding Material of case: system? (equivalent to UL94V-1) Synchronization system: Start-stop synchronization system RS-232C The longest: 15 m RS-485 The longest 500 m (depending on External dimensions: Communication distance: SR91: H48 × W48 × D111 (Panel depth: 100) mm conditions) SR92: H72 × W72 × D111 (Panel depth: 100) mm 1200, 2400, 4800, 9600, 19200 bps SR93: H96 × W96 × D111 (Panel depth: 100) mm • Communication speed: SR94: H96 × W48 × D111 (Panel depth: 100) mm • Data format: 7 bits, even parity, 1 stop bit or 8 bits, non-parity, 1 stop bit • Mounting: Push-in panel (one-touch mount) 1.0~4.0 mm Communication address: Panel thickness: 1~255 • Communication memory mode: EEP/RAM/r\_E Panel cutout: SR91: H45 × W45 mm Add/Add two's cmp/XOR/None SR92: H68 × W68 mm Communication BCC: SR93: H92 × W92 mm Communication delay time: 1~100 (× 0.512 msec) • Communication code: ASCII code SR94: H92 × W45 mm • Weight: Communication protocol: Shimaden's standard protocol SR91: Approximately 170 g SR92: Approximately 280 g • Number of connectable instruments: RS-232 1 SR93: Approximately 330 g RS-485 up to 31 SR94: Approximately 240 g • Isolation: Communication signals insulated from

system, each input and each output.

ITEM		СО	ODE					SPECIFICATIONS				
SERIES	SR91-							MPU-Based Auto-Tuning PID Digital Controlle	er, DIN H	148× W48×D110mm		
			Multi input					Thermocouple: B, R, S, K, E, J, T, N, PLII, W R.T.D.: Pt100 $\Omega$ /JPt100 $\Omega$	re5-26 {L	J, L (DIN 43710)}		
		8		iviu	шпр	ut		Voltage: -10~10, 0~10, 0~20, 0~50, For voltage and current inp				
INPUT								10~50, 0~100mV DC	Scali	ng Possible		
1141 01		4						Current (mA): 0~20, 4~20mA DC	Rang	ge: -1999~9999		
								Receiving impedance: 250 Ω	Spar	n: 10~5000		
		6						Voltage (V): -1~1, 0~1, 0~2, 0~5,	Note	: Inverse scaling		
								1~5, 0~10V DC		is not possible		
			Y-					Contact: 1a, Contact capacity: 240V AC 2.5A	/resistive	load		
			•					Proportional cycle: 1~120 sec.				
			I-					Current: 4~20mA DC				
CONTRO	L OUTPUT	(1)	-					Load resistance: 600 Ωmax.				
CONTINO	L 0011 01	(1)	P-					SSR drive voltage: 12V 1.5V DC/30mA max.				
								Proportional cycle: 1~120 sec.				
			V-				Voltage: 0~10V DC					
								Load current: 2mA max.				
POWER S	SLIPPLY		9	90-				100~240V AC 10%, 50/60Hz				
TOWLK	JOFFET		(	08-				24V AC/DC 10%, 50/60Hz				
EVENT C	LITDLIT (O	DTIC	) (IAC		0			None				
EVENTO	UTPUT (O	- 110	JIN)		1			Contact output (2a) Ev1, Ev2: 240V AC 1A/resistive load				
						Ν		None				
						Υ		Contact: 1a, Contact capacity: 240V AC 2.5A/resistive load				
								Proportional cycle: 1~120 sec.				
								Current: 4~20mA DC				
	C	ontro	ol outp	out (	2)			Load resistance: $600  \Omega$ max.				
		Ontic	or outp	out (	_,	Р		SSR drive voltage: 12±1.5V DC/30mA max.				
							Proportional cycle: 1~120 sec.					
						V		Voltage: 0~10V DC				
OPTION						v		Load current: 2mA max.				
	l l	eate				1		Current setting range: 0.1~30.0A (with CT 30.	A)	Note: Avaialble only when control output (1)		
		cato	i bica	r break alarm 2				Current setting range: 0.1~50.0A (with CT 50.	A)	is Y or P and when event output is selected.		
						3		Voltage: 0~10mV DC, Output resistance: 10 Ω				
	A	nalo	g outp	ut		4		Current: 4~20mA DC, Load resistance: 300 Ωmax.				
				6				Voltage: 0~10V DC, Load current: 2mA max.				
	С	omm	nunica	tion		5		RS-485				
	0	Set value bias			8		1 point (setting range: -1999~5000), Non-volt	1 point (setting range: -1999~5000), Non-voltage contact or Open collector input				
		ei va	iiue Di	as		0		Open collector input rating: approx. 5V/1mA max.				
REMARK	9						0	Without				
VEINIVI	J						9	With (Please consult before ordering.)				

#### Note:

When you purchase a two-output type controller and use it in a one output capacity, larger overshooting or undershooting may happen as a result of integral operation. Therefore, we recommend you to choose a one-output type.

The cause of the above-mentioned problem is that the positional relationship between the proportional band (PB) and the set value (SV) of a one-output type controller differs from that of a two-output type.

ITEM	EM CODE									SPECIFICATIONS				
SERIES	SR92-									MPU-Based Auto-Tuning PID Digital Controller, DIN H72 × W72 × D110mm				
8			N	Multi input						Thermocouple: B, R, S, K, E, J, T, N, PLII, Wre5-26 {U, L (DIN 43710)} R.T.D.: Pt100 $\Omega$ /JPt100 $\Omega$				
INDLIT			IVI	мин три						Voltage (mV): -10~10, 0~10, 0~20,				
INPUT		4								Range: -1999~9999				
		4									Span: 10~5000			
	6								Voltage (V): -1~1, 0~1, 0~2, 0~5, 1~5,	Note: Inverse scaling				
		Ü								0~10V DC Input resistance: 500kΩ min.	is not possible.			
			Y-							Contact: 1a, Contact capacity: 240V AC 2A/resist	tive load			
			_	_						Proportional cycle: 1~120 sec.				
			I-							Current: 4~20mA DC				
CONTROL	OUTPUT (	(1)		_						Load resistance: 600Ω max.				
	·	` '	P-	-					SSR drive voltage: 12V±1.5V DC/30mA max.					
			_						$\dashv$	Proportional cycle: 1~120 sec.				
			V-	V-						Voltage: 0~10V DC				
				N-		—	—		$\dashv$	Load current: 2mA max.  None				
				14-					$\dashv$	Contact: 1a, Contact capacity: 240V AC 2A/resist	tive load			
				Y-						Proportional cycle: 1~120 sec.	ive load			
									$\dashv$	Current: 4~20mA DC				
	OUTPUT (	(2)		I-	I-					Load resistance: $600\Omega$ max. (RA when shipped)				
(OPTION)										SSR drive voltage: 12V±1.5V DC/30mA max.				
				P-						Proportional cycle: 1~120 sec.				
				V						Voltage: 0~10V DC				
				V-	V-					Load current: 2mA max.				
ם אינים	LIDDI V				90-					100V~240V AC±10%, 50/60Hz				
POWER S	UPPLY				08-					24V AC/DC±10%, 50/60Hz				
						0				None				
						1				Event output (2a) Ev1, Ev2				
EVENT O	ITDI IT/					'				Contact capacity: 240V AC 1A/resistive load				
	BREAK ALA	ARM	(OI	PTIC	ON)	2				Event output (Ev1) + Heater break alarm (with CT30	Note: Available only when control output (1)			
						3				Event output (Ev1) + Heater break alarm (with CT50	DA) is Y or P is selected.			
							0			None				
	ANALOG OLITPLIT (OPTION)						3			Voltage: 0~10mV DC, Output resistance: 10Ω				
AINALOG	ANALOG OUTPUT (OPTION)				ļ	4			Current: 4~20mA DC, Load resistance: 300Ω max.					
							6			Voltage: 0~10V DC, Load current: 2mA max.				
								0		None				
00144	IOATION O	D 0	.,-		(0.55	-101		5	$\dashv$	RS-485				
COMMUN	ICATION O	K S	vВ	JIAS	(OPT	ION	'	7	$\dashv$	RS-232C				
	8							8		1 point (setting range: -1999~5000), Non-voltage contact or Open collector input				
									0	Open collector input rating: approx. 5V/1mA max.				
REMARKS	3							ŀ	0	With (Places consult before ordering )				
9								9	With (Please consult before ordering.)					

#### Note:

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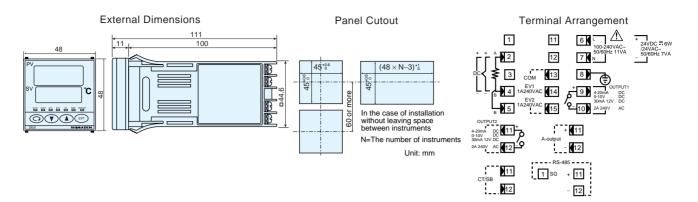
ITEM	M CODE							SPECIFICATIONS						
OFDIFO	SR	93-								MPU-Based Auto-Tuning PID Digital Controller, DIN H96 × W96 × D110mm				
SERIES	SR	94-								MPU-Based Auto-Tuning PID Digital Controller, DIN H96 × W48 × D110m				
					Thermocouple: B, R, S, K, E, J, T, N, PLII, Wre5-26 (U, L (DIN 43710))									
					lti inn	N. 14				R.T.D.: Pt100Ω /JPt100Ω				
			8	IVIU	Multi input					Voltage: -10~10, 0~10, 0~20,	voltage and current input:			
INDLIT										0~50, 10~50, 0~100mV DC	Scal	ing Possible		
INPUT			1							Current (mA): 0~20, 4~20mA DC	Ran	ge: -1999~9999		
			4							Receiving impedance: 250Ω	Span: 10~5000			
			_							Voltage (V): -1~1, 0~1, 0~2, 0~5, 0~10V DC Note: Inverse scaling				
			6							Load resistance: 600Ω max.	is not possible			
				Y-						Contact: 1a, Contact capacity: 240V AC 2A/resi	stive	load		
				_						Proportional cycle: 1~120 sec.				
				I-						Current: 4~20mA DC				
CONTRO	OLIT	PI IT (	1)	•						Load resistance: 600Ω max.				
CONTINO	_ 001		. 1 /	P-						SSR drive voltage: 12V±1.5V DC/30mA max.				
				·						Proportional cycle: 1~120 sec.				
				V-						Voltage: 0~10V DC				
										Load current: 2mA max.				
					N-					None				
					Υ-					Contact: 1a, Contact capacity: 240V AC 2A/resistive load				
					Υ-					Proportional cycle: 1~120 sec.				
CONTRO	OUT	PLIT (	2)		I-					Current: 4~20mA DC				
(OPTION)			<i>(-)</i>							Load resistance: 600Ω max.				
,					P-					SSR drive voltage: 12V±1.5V DC/30mA max.  Proportional cycle: 1~120 sec.				
										Voltage: 0~10V DC				
					V-									
						90-				Load current: 2mA max. 100~240V AC±10%, 50/60Hz				
POWER S	SUPPL	_Y				08-				24V AC/DC±10%, 50/60Hz				
						00-	0			None				
							-			Event output (2a) Ev1, Ev2				
							1			Contact capacity: 240V AC 1A/resistive load				
EVENT O			<b>D.</b> 4	(OD								Note: Available only		
HEATER I	BREA	K ALA	KIM	(OP	HON	1)	2	2		Event output (Ev1) + Heater break alarm (with CT3	30A)	when control output (1) is Y or P is selected.		
						3								
							3			Event output (Ev1) + Heater break alarm (with CT5				
								00		None				
								30		Voltage: 0~10mV DC, Output resistance: 10Ω				
		Ana	log (	outpu	ıt			40		Current: 4~20mA DC, Load resistance: 300Ω max.				
								60		Voltage: 0~10V DC, Load current: 2mA max.				
	Octobro bice (O.V.bice)			٥/	08		1 point (setting range: -1999~5000), Non-voltage of							
Set value bias (S V bias) OPTION			5)	00		Open collector input rating: approx. 5V/1mA max.								
					38		Voltage: 0~10mV DC, Output resistance: 10Ω							
								30		SV bias 1 point				
		alog output +					48		Current: 4~20mA DC, Load resistance: 300Ω max.					
		e bias (S V bias)						SV bias 1 point						
								68		Voltage: 0~10V DC, Load current: 2mA max.				
										SV bias 1 point				
		Con	nmu	nicati	on			05		RS-485				
								07	_	RS-232C				
REMARKS	3								0	Without				
									9	With (Please consult before ordering.)				

### Note:

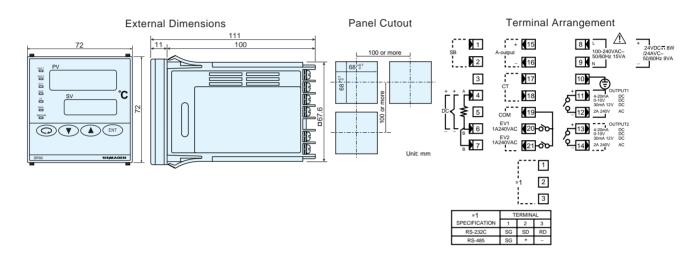
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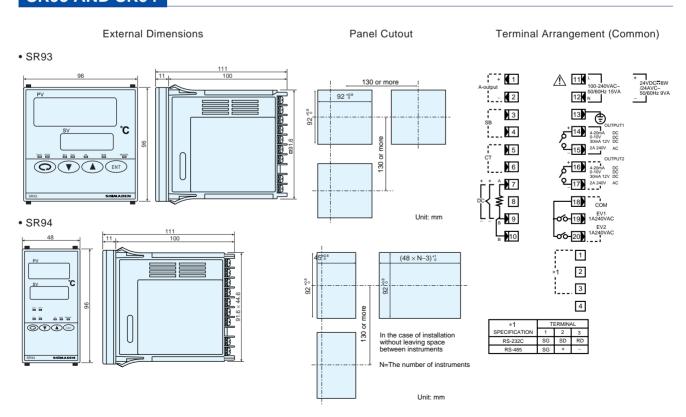
SR91 Series SR90



## **SR92**



## SR93 AND SR94



#### **MEASURING RANGE CODES**

	Input 7	Type	Code	Measuring ra	ange (°C)	Measuri	na ra	ange (°F)
		В *1	01	0 ~	1800	0	~	3300
		R	02	0 ~	1700	0	$\sim$	3100
		S	03	0 ~	1700	0	$\sim$	3100
		K	04 *2	-199.9 ~	400.0	-300	$\sim$	750
		K	05	0.0 ~	800.0	0	~	1500
		K	06	0 ~	1200	0	$\sim$	2200
	Thermo-	E	07	0 ~	700	0	$\sim$	1300
	couple	J	08	0 ~	600	0	$\sim$	1100
	couple	Т	09 *2	-199.9 ~	200.0	-300	$\sim$	400
		N	10	0 ~	1300	0	$\sim$	2300
		PLII *3	11	0 ~	1300	0	$\sim$	2300
l		WRe5-26*4	12	0 ~	2300	0	$\sim$	4200
Multi-input		U *5	13 *2	-199.9 ~	200.0	-300	$\sim$	400
:=		L *5	14	0 ~	600	0	$\sim$	1100
Į₹			31	-200 ~	600	-300	$\sim$	1100
2		D+4.00	32	-100.0 ~	100.0	-150.0	$\sim$	200.0
		Pt100	33	-50.0 ~	50.0	-50.0	$\sim$	120.0
	R.T.D.		34	0.0 ~	200.0	0.0	$\sim$	400.0
	K.1.D.		35	-200 ~	500	-300	$\sim$	1000
		Jpt100	36	-100.0 ~	100.0	-150.0	$\sim$	200.0
		JP1100	37	-50.0 ~	50.0	-50.0	$\sim$	120.0
			38	0.0 ~	200.0	0.0	$\sim$	400.0
		-10 ~ 10	71	Scaling possi	ible	NOTE:		
		0 ~ 10	72	] "			otherv	wise specif
	Voltage	0 ~ 20	73	Refer to the i	nformation			ipment fro
	(mV)	0 ~ 50	74	on the right.				1
		10 ~ 50	75				npu	.
		0~100	76			'	при	١
		-1 ~ 1	81					
		0 ~ 1	82			Mu	lti-in	put
$  v_0  $	oltage (V)	0 ~ 2	83					
``	- · · · · · · · · · · · · · · · · · · ·	0 ~ 5	84			\/a!	tage	. , , ,
		1 ~ 5	85			VOI	iage	; (V)
_		0 ~ 10	86					
Cu	rrent (mA)	0 ~ 20	91			Curr	ent (	(mA)
ı~u	(//)	4 ~ 20	92	I			,	` ′

Owing to scaling function, any measuring range can be set within the following range.

Scaling range: -1999 to 9999 counts

10 to 5000 counts on condition of Span:

lower side < higher side

Thermocouple:

B: Accuracy guarantee not applicable to 400°C (752°F) and below.

\*2 Thermocouple

K, T, U: Accuracy of those whose readings are below -100°C is ±0.7% FS

Thermocouple PLII: Platinel

\*4 Thermocouple

Wre5-26: A product of Hoskins

\*5 Thermocouple U, L: DIN 43710

otherwise specified, the measuring range will be set as listed below the shipment from the factory

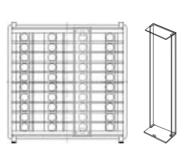
Input	Specification/Rating	Measuring range
Multi-input	K thermocouple	0.0 ~ 800.0°C
Voltage (V)	0 ~ 10V DC	0.0 ~ 100.0
Current (mA)	4 ~ 20mA DC	0.0 ~ 100.0

## TERMINAL COVER (AVAILABLE SEPARATELY)

ľ	Model	Mounting
SR91	QCR001	One-touch mount
SR92	QCR002	One-touch mount
SR93	QCR003	One-touch mount

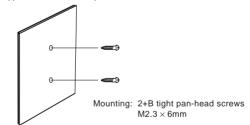
20

Material/Appearance: PVC/transparent



	Model	Mounting			
SR94	QCR004 (Individual mounting)	Plus screw, B tight, M2.3 × 6 - 2 pcs.			
SK94	QCR005 (Tight-lock coupling)	Plus screw, B tight, M2.3 × 6 - 4 pcs.			

Material/Appearance: PVC/transparent Thickness: 1 mm



#### Warning

 The SR90 series is designed for the control of temperature, humidity and other physical values of general industrial equipment. (It is not to be used for any purpose which regulates the prevention of serious effects on human life or safety.)

#### Caution

• If the possibility of loss or damage to your system or property as a result of failure of any part of the process exists, proper safety measures must be made before the instrument is put into use so as to prevent the occurrence of trouble.





ISO 9001

(The contents of this brochure are subject to change without notice.)

**Temperature and Humidity Control Specialists** 

# CO..LT

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